

STUDENT NAME:

Linear Algebra Graduate Comprehensive Exam, August 2016
Worcester Polytechnic Institute

Work out at least 6 of the following problems
Write down detailed proofs of every statement you make.
No Books. No Notes. No calculators.

1. Show that zero is an eigenvalue of the following matrix:

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & -1 & -1 & 4 & -1 \\ -1 & -1 & -1 & -1 & 0 & 0 & 0 & 0 & -1 & 5 \end{bmatrix}$$

What is its multiplicity? Does the matrix have nonzero eigenvalues? If so, compute their product. If not, explain why not.

2. Let $L : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation and for every $k \in \mathbb{N}$, denote by L^k the composition of L with itself k times.

(i) Show that for every $k \in \mathbb{N}$, one has

$$\text{Range}(L^{k+1}) \subseteq \text{Range}(L^k)$$

(ii) Show that there exists a positive integer m such that for all $k \geq m$ one has

$$\text{Range}(L^k) = \text{Range}(L^{k+1})$$

(iii) For m as in (ii) set $W = \text{Range}(L^m)$. What can you deduce about the restriction of the map L to the subspace W ?

3. For every two continuous functions $f, g \in C(\mathbb{R})$ define their product to be

$$\langle f, g \rangle := \int_{-1}^1 f(x)g(x)dx.$$

Show that this defines an inner product on the space of all continuous functions $C(\mathbb{R})$.

4. Consider the space V_3 of polynomials with real coefficients of degree at most 3. Find a basis for V_3 such that
- (i) every element of the basis satisfies $p(1) = 1$
 - (ii) any two elements in the basis have different degrees
 - (iii) any two elements in the basis are orthogonal with respect to the scalar product introduced in the previous problem.
5. Consider $T : \mathbb{P}_3 \rightarrow \mathbb{P}_1$ defined by second differentiation, i.e., by $T(p) = p'' \in \mathbb{P}_1$ for $p \in \mathbb{P}_3$. Find the matrix representation of T with respect to the bases $\{1 + x, 1 - x, x + x^2, x^2 - x^3\}$ for \mathbb{P}_3 and $\{1, x\}$ for \mathbb{P}_1 .
6. Consider the following matrix

$$A = \frac{1}{2} \begin{bmatrix} 0 & -3 & 0 & 1 \\ -3 & 0 & -1 & 0 \\ 0 & 1 & 0 & 5 \\ -1 & 0 & 5 & 0 \end{bmatrix}$$

- (i) Find the transformation matrix M , and its inverse, such that $J = MAM^{-1}$ is the Jordan canonical form of A .
 - (ii) What is the characteristic polynomial of the matrix A ?
 - (iii) Find all possible Jordan canonical forms of a matrix with the same characteristic polynomial as A .
7. Consider the system $Ax = b$, where A is $m \times n$ with $m < n$ and $\text{rank}(A) = m$.
- (i) Describe the set of all solutions of the system.
 - (ii) Show that (AA^T) is nonsingular.
 - (iii) Show that $A^T(AA^T)^{-1}b$ is the minimum-norm solution of the system.